



## Math 240 Midterm 1

Name: \_\_\_\_\_ SOLUTIONS \_\_\_\_\_

There are 8 questions plus one extra credit question. The questions are weighted differently. Make sure you check all your answers before attempting the extra credit question.

For grading purposes:

1: \_\_\_\_\_  
2: \_\_\_\_\_  
3: \_\_\_\_\_  
4: \_\_\_\_\_  
5: \_\_\_\_\_  
6: \_\_\_\_\_  
7: \_\_\_\_\_  
8: \_\_\_\_\_  
EC: \_\_\_\_\_

Total: \_\_\_\_\_

1. (10 points) Solve the system of equations

$$x + y + 3z = 6$$

$$x - y + 2z = 1$$

$$2x + y + 9z = 13$$

Answer:  $\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix}$

In matrix form:

$$\begin{pmatrix} 1 & 1 & 3 & | & 6 \\ 1 & -1 & 2 & | & 1 \\ 2 & 1 & 9 & | & 13 \end{pmatrix} \xrightarrow{R_3 \leftarrow R_3 - 2R_1} \begin{pmatrix} 1 & 1 & 3 & | & 6 \\ 1 & -1 & 2 & | & 1 \\ 0 & -1 & 3 & | & 1 \end{pmatrix} \xrightarrow{R_2 \leftarrow R_2 - R_1} \begin{pmatrix} 1 & 1 & 3 & | & 6 \\ 0 & -2 & -1 & | & -5 \\ 0 & -1 & 3 & | & 1 \end{pmatrix}$$

$$R_3 \leftarrow R_3 \times 2 \xrightarrow{} \begin{pmatrix} 1 & 1 & 3 & | & 6 \\ 0 & -2 & -1 & | & -5 \\ 0 & -2 & 6 & | & 2 \end{pmatrix} \xrightarrow{R_3 \leftarrow R_3 - R_2} \begin{pmatrix} 1 & 1 & 3 & | & 6 \\ 0 & -2 & -1 & | & -5 \\ 0 & 0 & 7 & | & 7 \end{pmatrix} \xrightarrow{R_3 \leftarrow \frac{R_3}{7}} \begin{pmatrix} 1 & 1 & 3 & | & 6 \\ 0 & -2 & -1 & | & -5 \\ 0 & 0 & 1 & | & 1 \end{pmatrix}$$

$$R_2 \leftarrow R_2 + R_3 \xrightarrow{} \begin{pmatrix} 1 & 1 & 0 & | & 3 \\ 0 & -2 & 0 & | & -4 \\ 0 & 0 & 1 & | & 1 \end{pmatrix} \xrightarrow{R_2 \leftarrow \frac{R_2}{-2}} \begin{pmatrix} 1 & 1 & 0 & | & 3 \\ 0 & 1 & 0 & | & 2 \\ 0 & 0 & 1 & | & 1 \end{pmatrix} \xrightarrow{R_1 \leftarrow R_1 - R_2} \begin{pmatrix} 1 & 0 & 0 & | & 1 \\ 0 & 1 & 0 & | & 2 \\ 0 & 0 & 1 & | & 1 \end{pmatrix}$$

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix}$$

2. (10 points) Find the function  $y(x)$  that satisfies

$$x^2 y'' - 6xy' + 12y = 0$$

with  $y(1) = 0$  and  $y'(1) = 2$

$$y(x) = -2x^3 + 2x^4$$

Cauchy-Euler equation. Try  $y = x^m$

$$x^2 m(m-1)x^{m-2} - 6xm x^{m-1} + 12x^m = 0$$

$$x^m (m^2 - m - 6m + 12) = 0$$

$$x^m (m^2 - 7m + 12) = x^m (m-3)(m-4)$$

$$\text{so } m = 3 \text{ or } 4$$

$$y(x) = c_1 x^3 + c_2 x^4$$

$$y'(x) = 3c_1 x^2 + 4c_2 x^3$$

$$y(1) = 0 \Rightarrow c_1 + c_2 = 0$$

$$y'(1) = 2 \Rightarrow 3c_1 + 4c_2 = 2$$

$$\Rightarrow \begin{matrix} c_2 = 2 \\ c_1 = -2 \end{matrix}$$

$$y(x) = -2x^3 + 2x^4$$

$$\begin{matrix} y' = m x^{m-1} \\ y'' = m(m-1)x^{m-2} \end{matrix}$$

3. (15 points) Find the general solution to the differential equation

$$\frac{d^4 y}{dx^4} - 7 \frac{d^3 y}{dx^3} + 12 \frac{d^2 y}{dx^2} = 6$$

$$y(x) = C_1 + C_2 x + C_3 e^{3x} + C_4 e^{4x} + \frac{1}{4} x^2$$

Linear equation with constant coefficients.

Try  $y = e^{mx}$        $y' = m e^{mx}$ ,  $y'' = m^2 e^{mx}$ ,  $y''' = m^3 e^{mx}$ ,  $y^{(4)} = m^4 e^{mx}$

$$m^4 e^{mx} - 7m^3 e^{mx} + 12m^2 e^{mx} = 0 \quad (\text{homogeneous version of the equation})$$

$$e^{mx} (m^4 - 7m^3 + 12m^2) = 0$$

$$e^{mx} m^2 (m^2 - 7m + 12) = 0$$

$$e^{mx} m^2 (m-3)(m-4) = 0$$

$m_1 = m_2 = 0$  is a double root.  $m_3 = 3$      $m_4 = 4$

$$\begin{aligned} \text{So } y_c(x) &= C_1 e^{0x} + C_2 x e^{0x} + C_3 e^{3x} + C_4 e^{4x} \\ &= C_1 + C_2 x + C_3 e^{3x} + C_4 e^{4x} \end{aligned}$$

For  $y_p$ , try  $y = Ax^2$      $y' = 2Ax$      $y'' = 2A$      $y''' = 0$      $y^{(4)} = 0$

Plug in:  $0 - 7 \cdot 0 + 12 \cdot 2A = 6$

$$A = \frac{1}{4}$$

$$y_p = \frac{1}{4} x^2$$

$$y = y_p + y_c = \frac{1}{4} x^2 + C_1 + C_2 x + C_3 e^{3x} + C_4 e^{4x}$$

4 (10 points) Find  $\det(A^{-1}BA)$  for

$$A = \begin{pmatrix} 1 & 0 & 0 \\ -5 & -2 & 0 \\ 3 & -5 & 3 \end{pmatrix}$$

and

$$B = \begin{pmatrix} 1 & 2 & 3 \\ -4 & -2 & 0 \\ 3 & -1 & 2 \end{pmatrix}$$

$\det(A^{-1}BA) =$

$$\begin{aligned} \text{We have } \det(A^{-1}BA) &= \det(A^{-1}) \det(B) \det(A) \\ &= \det(A^{-1}) \det(A) \det(B) \\ &= \det(\underbrace{A^{-1}A}_I) \cdot \det(B) = \det(B) \end{aligned}$$

$$\begin{aligned} \det(B) &= 1 \cdot ((-2)2 - 0 \cdot (-1)) - 2 \cdot ((-4)2 - 0 \cdot 3) + 3 \cdot ((-4)(-1) - (-2)3) \\ &= -4 + 16 + 30 = \blacksquare 42 \end{aligned}$$

5. (12 points) Find the solution to the system of differential equations

$$\begin{aligned}\frac{dx}{dt} &= 2x - y \\ \frac{dy}{dt} &= 2x + 5y\end{aligned}$$

that satisfies  $x(0) = 0$ ,  $y(0) = 1$ .

$$\begin{pmatrix} x(t) \\ y(t) \end{pmatrix} = \begin{pmatrix} 1 \\ -1 \end{pmatrix} e^{3t} + \begin{pmatrix} -1 \\ 2 \end{pmatrix} e^{4t}$$

in matrix form:  $X' = AX$     $X = \begin{pmatrix} x(t) \\ y(t) \end{pmatrix}$     $A = \begin{pmatrix} 2 & -1 \\ 2 & 5 \end{pmatrix}$

Find eigenvalues and eigenvectors

$$\det(A - \lambda I) = \det \begin{pmatrix} 2-\lambda & -1 \\ 2 & 5-\lambda \end{pmatrix} = (\lambda-3)(\lambda-4)$$

for  $\lambda=3$ :  $A-3I = \begin{pmatrix} -1 & -1 \\ 2 & 2 \end{pmatrix} \rightsquigarrow \begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix}$     $v_1 = -v_2$   
 $K_1 = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$

for  $\lambda=4$ :  $A-4I = \begin{pmatrix} -2 & -1 \\ 2 & 1 \end{pmatrix} \rightsquigarrow \begin{pmatrix} 2 & 1 \\ 0 & 0 \end{pmatrix}$     $2v_1 = -v_2$   
 $K_2 = \begin{pmatrix} -1 \\ 2 \end{pmatrix}$

so  $X = c_1 \begin{pmatrix} 1 \\ -1 \end{pmatrix} e^{3t} + c_2 \begin{pmatrix} -1 \\ 2 \end{pmatrix} e^{4t}$

$$X(0) = \begin{pmatrix} x(0) \\ y(0) \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \end{pmatrix} \Rightarrow c_1 \begin{pmatrix} 1 \\ -1 \end{pmatrix} + c_2 \begin{pmatrix} -1 \\ 2 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$\begin{aligned}\text{so } c_1 - c_2 &= 0 \\ -c_1 + 2c_2 &= 1 \Rightarrow c_1 = 1 \text{ and } c_2 = 1\end{aligned}$$

6. (15 points) Find the *general solution* to the system of differential equations given for functions  $x(t)$  and  $y(t)$  by

$$\begin{pmatrix} x' \\ y' \end{pmatrix} = \overbrace{\begin{pmatrix} 2 & 1 \\ 0 & 2 \end{pmatrix}}^A \begin{pmatrix} x \\ y \end{pmatrix}$$

$$\begin{pmatrix} x(t) \\ y(t) \end{pmatrix} = c_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix} e^{2t} + c_2 \left( \begin{pmatrix} 1 \\ 0 \end{pmatrix} t e^{2t} + \begin{pmatrix} 0 \\ 1 \end{pmatrix} e^{2t} \right)$$

$$\det(A - \lambda I) = \det \begin{pmatrix} 2 - \lambda & 1 \\ 0 & 2 - \lambda \end{pmatrix} = (\lambda - 2)^2$$

$\lambda = 2$  is an eigenvalue with multiplicity two.

$$A - 2I = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \Rightarrow K_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \text{ is the only eigenvector.}$$

$$\text{so } X = c_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix} e^{2t} + c_2 \left( \begin{pmatrix} 1 \\ 0 \end{pmatrix} t e^{2t} + P e^{2t} \right)$$

$$\text{where } (A - 2I)P = K_1$$

$$\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} P = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \text{ so } P = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

7. (18 points) TRUE or FALSE? You do not need to justify your answers

(i) The  $n \times n$  matrix whose entries are all equal to 1 has rank  $n$ .

(ii) For an  $n \times n$  matrix  $A$ , if  $\det(A) = 0$ , the the equation  $A\vec{v} = 0$  has infinitely many solutions.

(iii) If  $D$  is an  $n \times n$  diagonal matrix and  $A$  is any  $n \times n$  matrix, then  $AD = DA$ , that is,  $A$  and  $D$  commute.

(iv) For every two  $n \times n$  diagonal matrices  $D_1$  and  $D_2$ , we have  $D_1D_2 = D_2D_1$ . i.e. they commute.

(v) If two  $3 \times 3$  matrices  $A$  and  $B$  are diagonalizable with the same eigenvectors, then they commute.

(vi) Let  $A$  be a  $3 \times 3$  matrix with eigenvalues 1, 2 and 0. Then  $A$  is diagonalizable.

(vii) Let  $A$  be a  $3 \times 3$  matrix with eigenvalues 1, 2 and 0. Then  $A$  is invertible.

(viii) The subset  $\left\{ \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \in \mathbb{R}^3 \mid x_1 - 3x_2 + x_3 = 0 \right\}$  is a subspace of  $\mathbb{R}^3$ .

(ix) The subset  $\left\{ \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \in \mathbb{R}^2 \mid x_1x_2 = 0 \right\}$  is a subspace of  $\mathbb{R}^2$ .

(i) Such a matrix has all its rows  $(1 \ 1 \ \dots \ 1)$  so the rank is 1 not  $n$ . FALSE

(ii)  $\det A = 0 \Leftrightarrow A$  is singular  
 $\Leftrightarrow \text{rk} A < n \Leftrightarrow \text{nullity} A > 0$  TRUE

(iii) FALSE  $\begin{pmatrix} 2 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} = \begin{pmatrix} 2 & 2 \\ 1 & 1 \end{pmatrix}$

$\begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} 2 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 2 & 1 \\ 2 & 1 \end{pmatrix}$

(iv) true  $\begin{pmatrix} d_1 & & 0 \\ & d_2 & \\ 0 & & d_n \end{pmatrix} \begin{pmatrix} b_1 & & 0 \\ & b_2 & \\ 0 & & b_n \end{pmatrix} = \begin{pmatrix} d_1 b_1 & & 0 \\ & d_2 b_2 & \\ 0 & & d_n b_n \end{pmatrix}$


- |        |                                       |  |
|--------|---------------------------------------|--|
| (i)    | <input type="radio"/> true            | <input checked="" type="radio"/> false |
| (ii)   | <input checked="" type="radio"/> true | <input type="radio"/> false            |
| (iii)  | <input type="radio"/> true            | <input checked="" type="radio"/> false |
| (iv)   | <input checked="" type="radio"/> true | <input type="radio"/> false            |
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| (viii) | <input checked="" type="radio"/> true | <input type="radio"/> false            |
| (ix)   | <input type="radio"/> true            | <input checked="" type="radio"/> false |

(v) true.  $A = PD_1P^{-1}$   $B = PD_2P^{-1}$   $AB = PD_1P^{-1}PD_2P^{-1} = PD_1D_2P^{-1} = PD_2D_1P^{-1} = PD_2P^{-1}PD_1P^{-1} = BA$

(vi) three distinct eigenvalues gives three independent eigenvectors. TRUE

(vii) 0 is an eigenvalue so there is a  $\vec{v}$  st.  $A\vec{v} = 0 \cdot \vec{v} = 0$  so nullity  $A > 0$ . FALSE

(viii) TRUE this is a plane through the origin in  $\mathbb{R}^3$ .

(ix)  this is the union of the x axis and the y axis. not closed under addition  $\begin{pmatrix} 1 \\ 0 \end{pmatrix} + \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$  is not in the subset.



8. (10 points) Find the *general solution* to the differential equation

$$x^2 y'' + xy' = 0$$

$$y(x) = c_1 + c_2 \ln x$$

Cauchy-Euler equation.  $y = x^m$

$m(m-1) + m = 0$  is the auxiliary equation.

$$m^2 - m + m = m^2 = 0$$

$m=0$  is a double root.

$$y = c_1 x^0 + c_2 x^0 \ln x$$

$$= c_1 + c_2 \ln x$$

Extra Credit (15pts) Your answers must include complete justification. Please write sentences to explain your proof. Each part is 5 points, no partial credit will be given:

Recall that the image of an  $n \times n$  matrix  $A$  is:

$$\text{Im } A = \{\vec{w} \in \mathbb{R}^n \mid \vec{w} = A\vec{v} \text{ for some } \vec{v} \in \mathbb{R}^n\}$$

The kernel of  $A$  is the solution space to  $A\vec{v} = 0$ .

$$\text{Ker } A = \{\vec{v} \in \mathbb{R}^n \mid A\vec{v} = 0\}$$

- a) Show that, if there is an  $n \times n$  matrix  $A$  whose image is identical to its kernel, i.e.  $\text{Im } A = \text{Ker } A$ , then  $n$  must be even.  
 b) Give an example of such a matrix.  
 c) Let  $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$ . Think about  $A$  mapping the plane to the plane. In other words, think about the linear transformation  $\mathbb{R}^2 \rightarrow \mathbb{R}^2$  given by multiplying by  $A$ . What is the area of the image of the unit square  $\{(x, y) \in \mathbb{R}^2 \mid 0 < x < 1 \text{ and } 0 < y < 1\}$  under this linear transformation. You might need to use the fact that

$$|\vec{v} \times \vec{w}| = |\vec{v}||\vec{w}| \sin \alpha$$

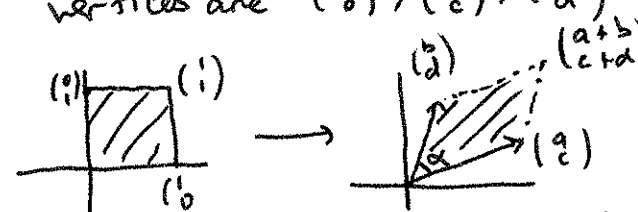
where  $\alpha$  is the angle between  $\vec{v}$  and  $\vec{w}$ . And if you forgot how to calculate cross products, you might need to use that

$$|\vec{v} \times \vec{w}| = v_1 w_2 - v_2 w_1$$

for  $\vec{v} = (v_1, v_2)$  and  $\vec{w} = (w_1, w_2)$ .

a)  $\text{rank } A = \text{dimension of the image of } A$   
 $\text{nullity} = \text{dimension of the kernel of } A$  so if  $\text{Im } A = \text{Ker } A$   
 then  $\text{rank } A = \text{nullity of } A$  so  $\text{rank } A + \text{nullity } A$  is even  
 " " " " so  $n$  is even

b) project onto x axis, then rotate by  $90^\circ$  counterclockwise  
 this takes  $\begin{pmatrix} 1 \\ 0 \end{pmatrix}$  to  $\begin{pmatrix} 0 \\ 1 \end{pmatrix}$  and  $\begin{pmatrix} 0 \\ 1 \end{pmatrix}$  to  $\begin{pmatrix} 0 \\ 0 \end{pmatrix}$   
 so  $A = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}$   $\text{Ker } A = \text{Im } A$  is the y axis

c) This matrix takes the unit square to the parallelogram whose vertices are  $\begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} a \\ c \end{pmatrix}, \begin{pmatrix} b \\ d \end{pmatrix}, \begin{pmatrix} a+b \\ c+d \end{pmatrix}$  Say  $\vec{v} = \begin{pmatrix} a \\ c \end{pmatrix}, \vec{w} = \begin{pmatrix} b \\ d \end{pmatrix}$   


The area of the parallelogram is base  $\times$  height. Base is  $|\vec{v}|$ , height is  $|\vec{w}| \sin \alpha$ .

So the area is  $|\vec{v} \times \vec{w}| = |ad - bc|$